

Real-World Issues and Applications for Real-time Geographic Information Systems (RT-GIS)

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What Is Real-time?

*"The performance of a computation during the actual time that the related physical process transpires, in order that results of the computation can be used in guiding the physical process."*¹

**Application
on
Depende**

¹IEEE, Software Engineering Standards, 3rd ed., 1990



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Key Functions of Real-Time Geographic Information Systems

- Manages spatial reference to data
- Provides continued access to database throughout query, retrieval, analysis, and information use
- Analysis functions are responsive enough to support a real-time process
- Overlays of vector and raster data
- Topological relationships are maintained

NRL's Primary RT-GIS Customer

- Naval Oceanographic Office,
Applied Hydrography Division N54
 - T-AGS 60 survey ships
 - Integrated survey system ISS-60
 - Increasing data volumes
 - Decrease in personnel
 - Currently using flat file management schema

NAVO N54 Needs

- Support for several standard data formats
- Support for ever increasing data volumes
- Object-oriented data model
- Dynamically reconfigurable surveying
- GIS functionality to analyze data in-situ
- Use of commercial off-the-shelf (COTS) software

Definition of Real-time

$$\mathbf{RT} = (1 / \mathbf{M}) \left[\mathbf{DI}(d_1, \dots, d_i) + \mathbf{TP}(t_1, \dots, t_j) + \mathbf{GIS}(f_1, \dots, f_k) + \mathbf{OV} \right]$$

where

DI = data ingestion time

TP = database transaction processing time

GIS = spatial analysis/display function time

OV = system overhead

M = coefficient (money spent for bettering system)

NRL Approach to RT-GIS

- Use COTS CORBA compliant tools
- Develop an Object-Oriented Data Model
- Maintain access to common COTS GIS
- Adopt Geospatial Information DataBase (GIDB) Framework
- Add GIS functionality to analyze data in-situ to the GIDB tools
- Incorporate data translators for GSF, DIGEST, and S57 into GIDB

Geospatial Information Database (GIDB) Framework

- Object-oriented
- COTS components (GemStone®)
- CORBA-compliant
 - Common Object Request Broker Architecture
 - Internet access across diverse platforms
- Spatially referenced
 - Some GIS analysis and display functionality

Benefits of OO Design and Database

- Code reuse through inheritance
- Representation of complex data structures
- Encapsulation
 - Data and methods are stored together
 - Easier to modify or extend system
- Shorter development time
- Fewer errors

COTS Issues

- Low initial cost
- Interoperability
- Flexibility
- Reduce risks of schedule and budget overrun
- Must integrate with existing hardware and software
- Must analyze integrity and security risks

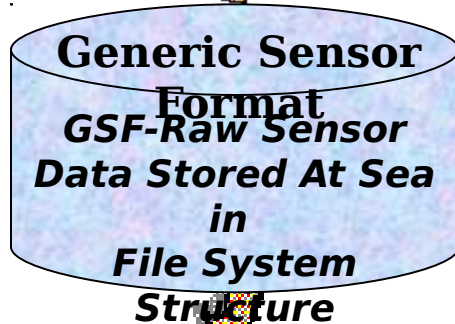
OO-Based Real-Time GIS Using GIDB

In-Situ Survey Ops

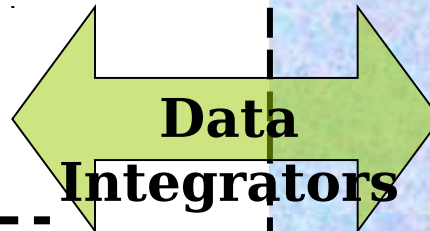
Framework



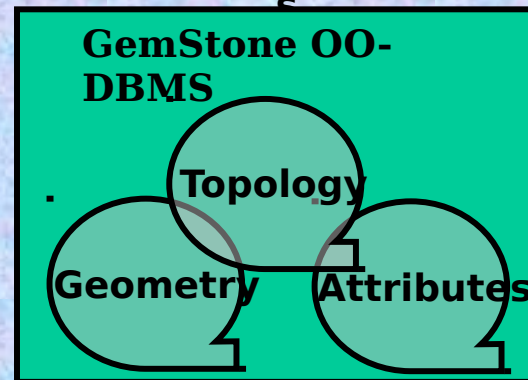
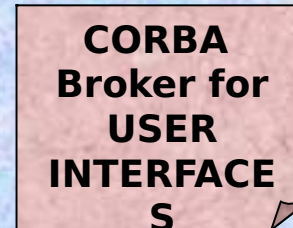
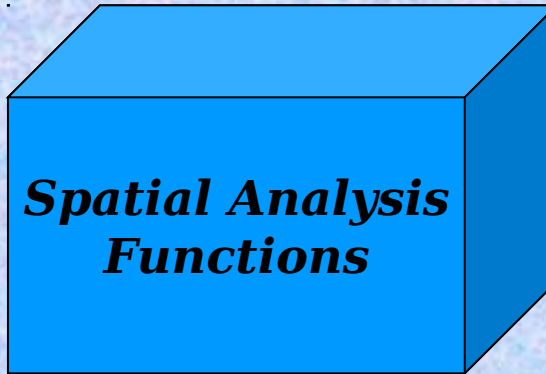
**Multi-Sensors
Data Output**



**On Land - Post
Processing & Data
Storage Systems**



**Real-Time GIS
Based on GIDB Framework**

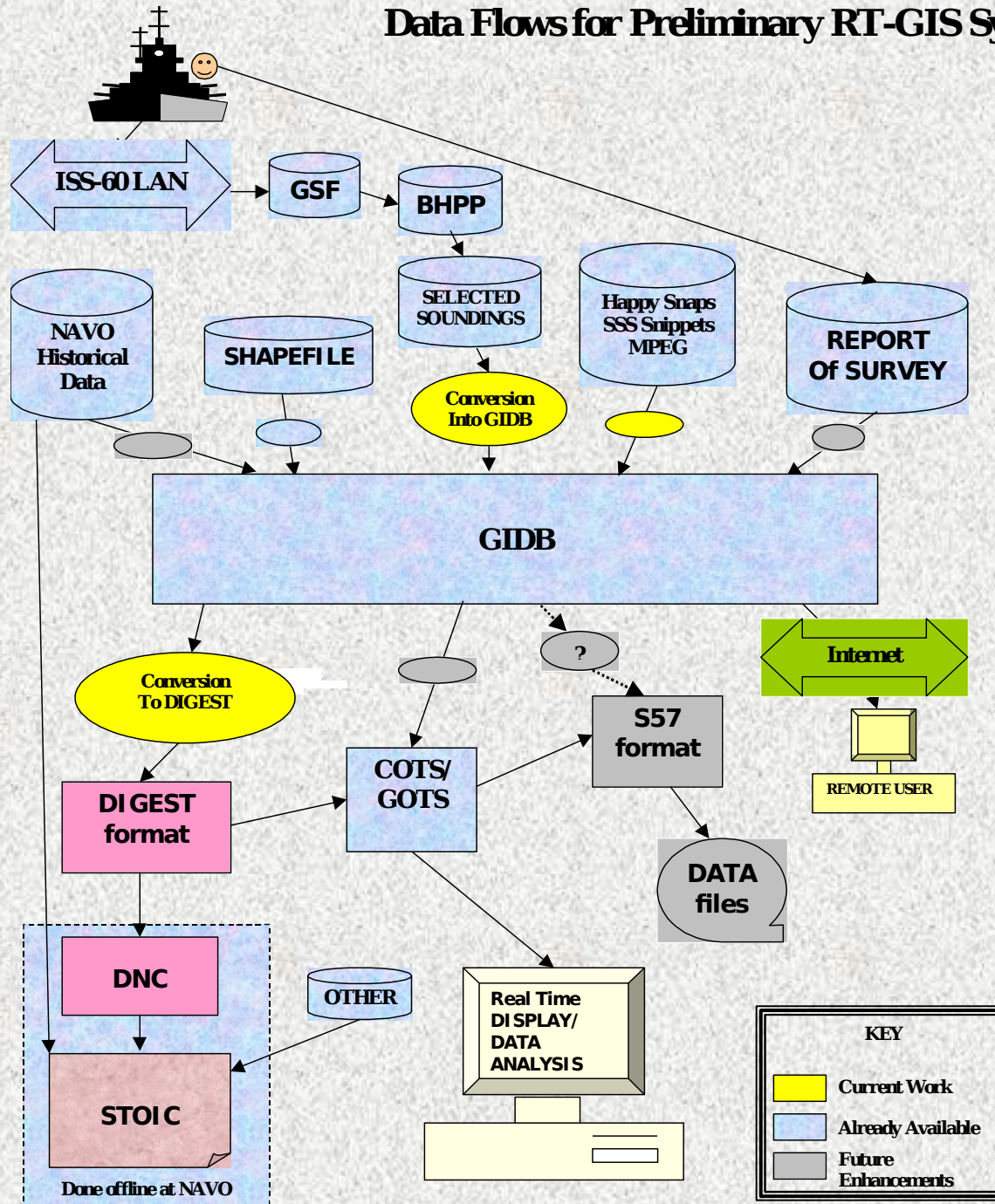


**Land Based
RT-GIS Interface**



**Ship Board LAN
or Intranet**

Data Flows for Preliminary RT-GIS System Design



Considerations for Vector Moving Map Displays

- RT-GIS needs to be integrated into real-time processes:
 - Navigation/Precise Positioning
 - Intelligence gathering
 - Mission planning
 - Improving situational awareness
 - Targetting
 - C4I

Impacts on RT-GIS for Vector Moving Map Displays

Copied from <http://mis.ncms.org/philc/HTML/Planes/modern>
Photo by Phil Callihan

Choice of data paradigm impacts

- Data performance and responsiveness

- Ability to add analysis functions

- Follow-on system design process

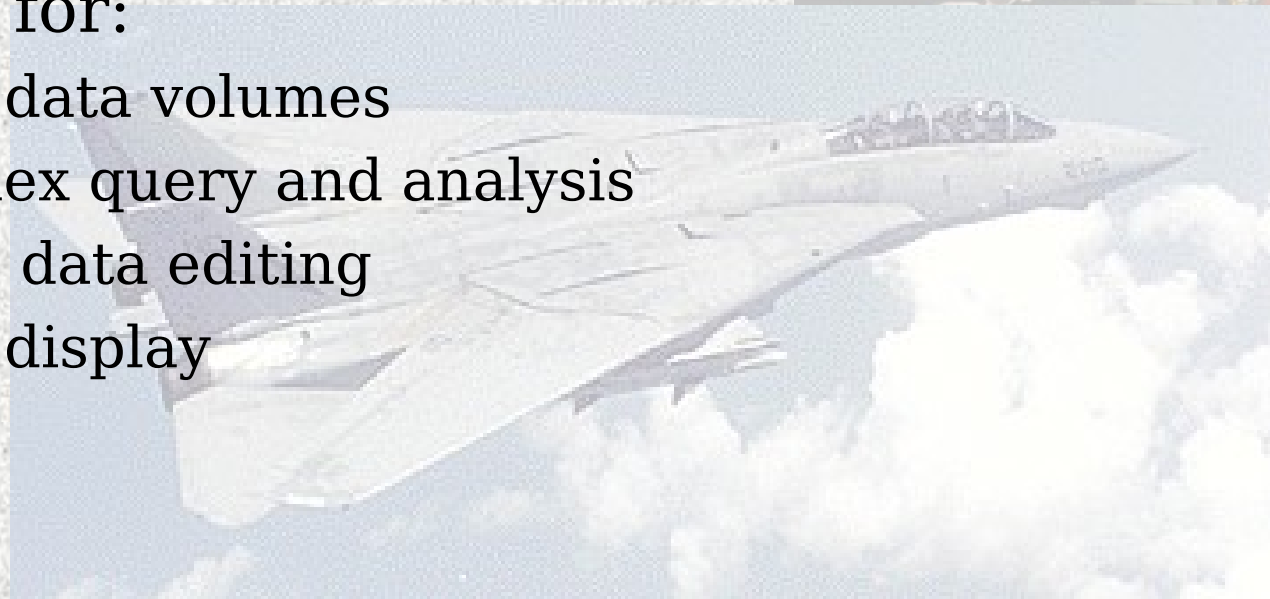
System costs increase proportionally to user needs for:

- Large data volumes

- Complex query and analysis

- In-situ data editing

- Rapid display



The background of the slide is a faded, high-angle photograph of an aircraft cockpit. A central display shows a map with a green highlighted area. Various instruments, dials, and control panels are visible around the display. The text is overlaid on this image.

GIS Requirements for Vector Moving Map Displays

- Maintain previously identified performance criteria
 - Display update/refresh rates
 - Switch map modes/scale changes
 - Quick reference to aircraft position
- Add new functionality unique to GIS:
 - Analysis functions on an active database
 - Complex query and change of area of interest
 - In-situ data editing using onboard sensors
 - Rapid display with query capability



Significant Influences on RT-GIS for Vector Moving Map Display

- Rate collection platform is capable of gathering and ingesting data
- Rate the user can receive and interpret data
- Rate of update required to maintain effective use of data

Conclusion

- Navy is steaming ahead to define real-time issues and impacts
- RT-Issues are very application dependent
- RT-GIS useful for Hydrographic Survey applications
- Hopeful that Real-Time issues can be quantified
- Vector Moving Map Display needs additional consideration as to real-time component